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PZ 62E User Manual

E-500/E-501 Series Modular Piezo Controller

Release: 2.15.1 Date: 2013-07-11

This document describes the following products:

■ E-500 and E-501 Chassis with Power Supply

■ E-503, E-504, E-505, E-506, E-508 Amplifier Modules

■ E-509 Sensor / Piezo Servo Control Modules

■ E-515 and E-517 Display / Interface Modules



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1. About this Document

1.1. Goal and Target Audience of this Manual

This manual contains information on the intended use of the E-500/E-501 series piezo control electronics (referred to as "E-500/E-501 system" in this manual).

It assumes that the reader has a fundamental understanding of basic servo systems as well as motion control concepts and applicable safety procedures.

The latest versions of the user manuals are available for download (p. 6) on our website.

1.2. Symbols and Typographic Conventions

The symbols and labels in this manual have the following definitions:

DANGER



Imminently hazardous situation

If not avoided, the hazardous situation will result in death or serious injury.

> Actions to be taken to avoid the situation.

NOTICE



Dangerous situation

If not avoided, the dangerous situation will result in damage to the equipment.

Actions to be taken to avoid the situation.

INFORMATION

Information for easier handling, tricks, tips, etc.

| Symbol/ Label | Meaning |
|------------------|---|
| 1. 2. | Action consisting of several steps whose sequential order must be observed |
| > | Action consisting of one or several steps whose sequential order is irrelevant |
| • | List item |
| p. 5 | Cross-reference to page 5 |
| RS-232 | Labeling of an operating element on the product (example: socket of the RS-232 interface) |
| Λ | Warning signs affixed to the product that refer to detailed information in this manual. |

1.3. Other Applicable Documents

Some of the devices which are mentioned in this documentation are described in detail in their own User Manuals or Technical Notes. The User Manuals and Technical Notes relevant for your configuration are included in delivery (see p. 14).

For the latest versions of the User Manuals and Technical Notes contact our customer service department (see p. 6).

| Device | Document |
|---|---|
| E-517 computer interface and display module | PZ214E User Manual Software manuals for E-517 are on the E-517 CD (e.g. the SM148E PIMikroMove manual). |
| E-509 sensor / servo-control module | PZ77E User Manual |
| E-802 servo-control submodule | PZ150E User Manual |
| E-801 sensor submodule | PZ117E User Manual |
| E-506 charge-controlled amplifier module | E506T0002 Technical Note |
| Analog controller LabView driver library and Hyperbit functionality | PZ181E Software Manual E500T0011 Technical Note with download instructions |
| E530B0008 power supply module for E-500 chassis | E530T0003 Technical Note |
| E531B0005 power supply module for E-501 chassis | E531T0004 Technical Note |

1.4. Downloading Manuals

INFORMATION

If a manual is missing on our website or if there are problems in downloading:

Contact our customer service department (info@pi.ws).

The current versions of the manuals are found on our website. To download a manual, proceed as follows:

- 1. Open the website http://www.pi-portal.ws.
- 2. Click Downloads.
- Click the corresponding category (e. g. *E Piezo Drivers & Nanopositioning Controllers*).
- 4. Click the corresponding product code (e. g. *E-517*).

An overview of the available file types is shown for the selected product.

- 5. If *(0 Files)* is shown in the *Documents* line, log in as follows to display and download the documents:
 - a) Insert the product CD in the corresponding PC drive.
 - b) Open the *Manuals* directory.
 - c) Open the Release News (e. g. *E-517_Releasenews_V_x_x_x.pdf*) on the CD of the product.
 - d) Find the user name and password in the **User login for software download** section in the Release News.
 - e) In the *User login* area on the left margin in the website, enter the user name and the password in the corresponding fields.
 - f) Click Login.

If **Documents (0 Files)** is still being displayed, no manuals are available:

- Contact our customer service department (info@pi.ws).
- 6. Click Documents.
- Click the desired manual and save it on the hard disk of your PC or on a data storage medium.

2. Safety

2.1. Intended Use

The E-500/E-501 system is a laboratory device according to DIN EN 61010. It is intended to be used in interior spaces and in an environment which is free of dirt, oil and lubricants.

Corresponding to its design, the E-500/E-501 system is intended for driving capacitive loads (e. g. piezo ceramic actuators).

The E-500/E-501 system must not be used for purposes other than those named in this user manual. In particular, the E-500/E-501 system must not be used to drive ohmic or inductive loads.

The E-500/E-501 system can be used for static as well as dynamic applications.

Capacitive sensors or strain gauge sensors must be used for closed-loop operation. PI stages intended for closed-loop operation already have the corresponding sensors. Other sensors can only be used with PI approval.

2.2. General Safety Instructions

The E-500/E-501 system is built according to state-of-the-art technology and recognized safety standards. Improper use can result in personal injury and/or damage to the E-500/E-501 system.

- Only use the E-500/E-501 system for its intended purpose, and only use it if it is in a good working order.
- Read the user manual.
- > Immediately eliminate any faults and malfunctions that are likely to affect safety.

The operator is responsible for the correct installation and operation of the E-500/E-501 system.

The E-500/E-501 system comes preinstalled and preconfigured. Removing modules from the chassis can result in personal injury and/or damage to the E-500/E-501 system.

- Only remove modules from the chassis when you are authorized and have the corresponding qualifications.
- ➤ Before removing modules from the chassis, remove the E-500/E-501 system from the power source by pulling the power plug.

2.3. Organizational Measures

User Manual

- ➤ Always keep this user manual next to the E-500/E-501 system when using the E-500/E-501 system.
 - If the user manual is lost or damaged, contact our customer service department (info@pi.ws).
- Add all information given by the manufacturer to the user manual, for example supplements or Technical Notes.
- ➤ If you pass the E-500/E-501 system on to other users, also turn over this user manual as well as other relevant information provided by the manufacturer.
- > Only use the device on the basis of the complete user manual. If your user manual is incomplete and is therefore missing important information, serious or fatal injury as well as property damage can result.
- ➤ Only install and operate the E-500/E-501 system after having read and understood this user manual.

Personnel Qualification

Only authorized and qualified personnel must install, operate, maintain and clean the E-500/E-501 system.

3. Introduction



Fig. 1: Three-channel system: E-501 chassis with E-509 sensor / piezo servo-control module, E-503 piezo amplifier module and E-517 interface / display module

3.1. Model Survey

Chassis

The E-500 and E-501 chassis are based on an EMI-proven chassis with multi-function power supply and a backplane carrying all connectors to the system amplifiers, servo-controllers and interface modules. E-500/E-501 systems are assembled to order, and tested with all your modules installed.

E-500.00 19"-Chassis for Modular Piezo Controller System, 1 to 3 channels, with E530B0008 Power Supply

E-501.00 9½"-Chassis for Modular Piezo Controller System, 1 to 3 channels, with E531B0005 Power Supply

Amplifier Modules

E-508.OE

| E-503.00 | Piezo Amplifier Module, -30 to 130 V, three channels | | |
|-----------|--|--|--|
| E-503.00S | Piezo Amplifier Module, -30 to 130 V, one of three channels is fixed (100 V) | | |
| E-504.00F | High-Power Piezo Amplifier Module, 1 channel, 280 W peak power, 100 W average | | |
| | power, -30 to 130 V | | |
| E-504.00S | High-Power Piezo Amplifier Module, 1 channel, 280 W peak power, 100 W average | | |
| | power, fixed voltage 100 V | | |
| E-505.00 | Piezo Amplifier Module, 2 A, -30 to 130 V, 1 channel | | |
| E-505.10 | Piezo Amplifier Module for switching applications, 10 A, -30 to 130 V, 1 channel | | |
| E-505.00S | 5.00S Piezo Amplifier Module, 1 channel, fixed voltage 100 V | | |
| E-506.10 | High Linearity Piezo Amplifier Module, 30 W average output power, -30 to 130 V, | | |
| | 1 channel | | |
| E-508.00 | HVPZT Piezo Amplifier Module,+3 to +1100 V, 1 channel | | |

HVPZT Piezo Amplifier Module, OEM version, 400 mA peak current, 1 channel

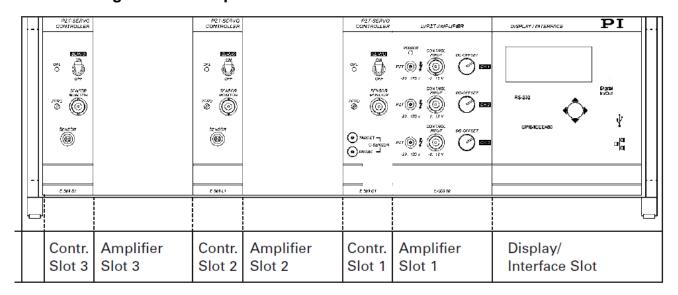
Sensor and Controller Modules

| E-509.S1 | Sensor / Piezo Servo-Control Module, SGS sensor, 1 channel |
|-----------|--|
| E-509.S3 | Sensor / Piezo Servo-Control Module, SGS sensors, 3 channels |
| E-509.S31 | Sensor / Piezo Servo-Control Module, SGS sensors, 3 channels, for NanoCube® stages |
| E-509.C1A | Sensor / Piezo Servo-Control Module, capacitive sensor, 1 channel |
| E-509.C2A | Sensor / Piezo Servo-Control Module, capacitive sensors, 2 channels |
| E-509.C3A | Sensor / Piezo Servo-Control Module, capacitive sensors, 3 channels |
| E-509.E3 | PISeca Sensor / Piezo Servo-Control Module for Single-Electrode Capacitive Sensor |
| | Probes, 3 Channels |
| E-509.E03 | PISeca Modular Signal Conditioner Electronics for Single Electrode Capacitive |
| | Sensors, 3 Channels |

Display and Interface Modules

| E-515.01 | Display Module for Piezo Voltage and Displacement, 1 channel |
|-----------|--|
| E-515.03 | Display Module for Piezo Voltage and Displacement, 3 channels |
| E-517.i1 | Interface / Display Module, 24 Bit D/A, TCP/IP, USB, RS232, IEEE 488, |
| | 1 channel |
| E-517.i10 | Interface / Display Module, 24 Bit D/A, TCP/IP, USB, RS232, 1 channel |
| E-517.i3 | Interface / Display Module, 24 Bit D/A, TCP/IP, USB, RS232, IEEE 488, |
| | 3 channels |
| E-517.i30 | Interface / Display Module, 24 Bit D/A, TCP/IP, USB, RS232, 3 channels |

3.2. Configuration Example



The figure above shows a three-channel configuration example consisting of the following components:

- E-500.00 chassis with power supply
- Amplifier Slot 1: E-503.00 three-channel amplifier module
- Amplifier Slots 2 and 3: not used, covered with dummy modules
- Contr. Slot 1: E-509.C1A single-channel sensor / servo-control module for capacitive sensor
- Contr. Slot 2 and 3: E-509.S1 single-channel sensor / servo-control modules for SGS sensors
- Display/Interface Slot: E-517.i3 three-channel interface / display module

3.3. Compatibility Note

NOTICE



Overheating or malfunction with improper system configuration!

In March 2011, the backplane of the chassis (E-500.00 or E-501.00) has been changed. The modules of the E-500/E-501 system have been adapted accordingly.

- "New" chassis and modules: date of manufacture is March 2011 or later
- "Old" chassis and modules: date of manufacture is before March 2011

If old and new components are to be combined in one system, modification of the chassis and/or modules by PI may be necessary for proper operation. Improper combination of old and new components in the E-500/E-501 system can cause damage by overheating or malfunction of the system.

With systems assembled by PI, the proper configuration is ensured. If you want to replace chassis or modules in your E-500/E-501 system:

> Contact our customer service department (p. 62).

3.4. Signal Path Diagram

The modules of the E-500/E-501 system can be combined in several configurations in an E-500 or E-501 chassis (see Section 3.2 for an example). The signal path diagram below shows a usual configuration.

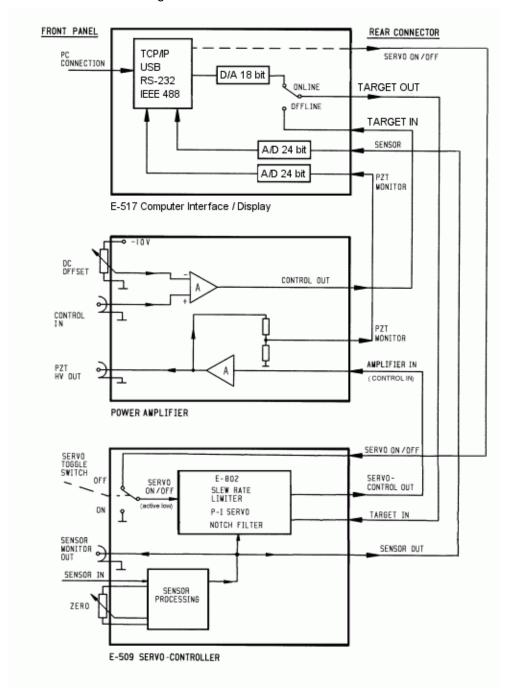


Fig. 2: Interconnections between E-517 digital piezo controller operation module, amplifier module and E-509 servo module

INFORMATION

The backplane of the chassis (E-500.00 or E-501.00) carries all connectors to the modules of the system (amplifiers, sensor / servo-control modules, interface /display modules).

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3.5. Maximum Ratings

The E-500/E-501 system is designed for the following operating data:

| Model | Maximum Operating Voltage | Operating Frequency | Maximum Current Consumption |
|--------------------------------|---|------------------------|-----------------------------|
| | \triangle | \triangle | \triangle |
| System in E- 500.00 chassis | 100 to 240 V~ (fuses: 2 x T2AH, 250 V) | 50-60 Hz | 210 VA |
| System in E- 501.00 chassis | 100 to 120 V~ (fuses: 2 x T2AH, 250 V | 50-60 Hz | 90 VA |
| | 220 to 240 V~ (fuses: 2 x T1AL, 250 V) | 50-60 Hz | 90 VA |

3.6. Ambient Conditions and Classifications

The following ambient conditions and classifications must be observed for the E-500/E-501 system:

| Area of application | For indoor use only |
|---|---|
| Maximum altitude | 2000 m |
| Relative humidity | Highest relative humidity 80 % for temperatures up to 31 °C |
| | Decreasing linearly to 50% relative humidity at 40°C |
| Storage temperature | 5 °C to 70 °C |
| Transport temperature | −25 °C to +85 °C |
| Overvoltage category | II |
| Protection class | I |
| Degree of pollution | 2 |
| Measurement category | 1 |
| Degree of protection according to IEC 60529 | IP20 |

4. Handling

4.1. Unpacking Checklist

The E-500/E-501 system was carefully inspected, both electrically and mechanically, before shipment. Upon receiving the device, unpack it and check for any obvious signs of physical damage that may have occurred during transit.

Retain and use the original packing material in case reshipment is necessary.

The following items are shipped with every E-500/E-501 system:

- · Chassis with modules installed.
- Power cord
- PZ62E User Manual (this document)
- E500T0011 Technical Note for GCS LabVIEW driver set for analog controllers

If one or more E-509 modules are installed, you should also have these items:

- PZ77E Manual for E-509
- With all models except for E-509.E03: PZ150E Manual for E-802 Servo-Controller Submodule
- With E-509.Sx and .S31 models only: PZ117E Manual for E-801 Sensor Submodule
- With E-509.S3 and .S31 models only: E-808.90 sensor monitor cable
- With E-509.CxA models only: PZ106E Manual for Capacitive Sensors
- With E-509.CxA, .E03 and .E3 models only: D-893.32 sensor monitor cable
- With E-509.E03 and .E3 models only: 3214 banana plug for ground connection of the sensor reference plane

If an E-517 module is installed, you should also have these items:

- C-815.34 RS-232 cable
- C-815.563 crossover network cable
- 000011448 USB cable
- 4347 and 4348 MDR connector for I/O socket
- E-517.CD product CD with software and manuals for E-517
- PZ214EQU User Manual for E-517, short version
- A000T0028 Technical Note for the PI Update Finder
- A000T0032 Technical Note for Using the PI Update Finder without Internet connection

4.2. Safety Measures for Installation, Start-Up and Operation

Improper installation of the E-500/E-501 system can result in personal injury and/or damage to the E-500/E-501 system.

- ➤ Install the E-500/E-501 system near the power source so that the power plug can be quickly and easily disconnected from the mains.
- ➤ Use the supplied power cord to connect the E-500/E-501 system to the power source.
- ➤ If the supplied power cord has to be replaced, use a sufficiently dimensioned component.
- Only use cables and connections that meet local safety regulations.

High temperatures can overheat the E-500/E-501 system.

- Install the E-500/E-501 system horizontally with 3 cm air circulation area.
- ➤ Do **not** install the E-500/E-501 system vertically since this prevents internal convection.
- > Ensure sufficient ventilation at the installation site.

The E-500.621 chassis uses the same main connectors as the E-500.00 and E-501.00, but has incompatible pinouts.

➤ Do not use the modules described in this manual with the E-500.621 chassis.

Oscillations can cause irreparable damage to the piezo actuator connected to the E-500/E-501 system. Oscillations are indicated by a humming and can result from the following causes:

- The load and/or dynamics of operation differ too much from the calibration settings.
- The piezo actuator is operated near its resonance frequency.

If you notice oscillations:

- > In closed-loop operation, immediately switch the servo mode off.
- In open-loop operation, immediately stop the piezo actuator.

The E-500/E-501 system performance can be reduced directly after power-on due to thermal instability.

> Switch the E-500/E-501 system on at least one hour before working with it.

The constant application of high voltage to piezos can lead to leakage currents and flashovers that destroy the ceramic.

If the E-500/E-501 system is not used, but should remain switched on to ensure the temperature stability.

- Switch the servo mode off (open-loop operation)
- Set the piezo voltage to 0 V:
 - Analog mode: The input voltage for the target value is 0 V
 - Computer-controlled mode: Corresponding commanding

4.3. Power Connection

The power connection is located on the rear panel of the chassis. Unless you request otherwise, the E-500/E-501 system will be set up for the line voltage we believe predominant in your country.

How to adapt E-500/E-501 system to a different line voltage:

- If your system uses a 19" chassis (E-500.00), it is equipped with a wide-range power supply and with fuses that are admissible for both 115 V and 230 V operation. No settings need be changed when connecting the device to a different line voltage.
- If your system uses a 9.5" chassis (E-501.00), it requires new fuses when it is to be connect to a different line voltage. Replace both fuses as described in "AC Power and Line Fuses" on p. 60.

4.4. First Electrical Checks

Check the device electrically when using it for the first time after unpacking. Perform these steps:

- 1. Connect the power cord.
- 2. Switch the device on without any piezo actuators connected. The power switch is at the rear next to the power cord socket.
- 3. Now the green LED on the amplifier module lights up.
- 4. If an E-517 Interface / Display module is installed:
 The display shows the main screen, see E-517 user manual for details.
- 5. Set the SERVO switch on the E-509 module to OFF.
- If an E-517 Interface / Display module is installed:
 Turn the DC-OFFSET potentiometer and watch the voltage display. The voltage reading is the current output voltage at the PZT output sockets.

The position values in the display have no meaning, because the piezo actuators and sensors are not yet connected.

If these steps could be performed without unexpected results, the device has passed the electrical checks.

4.5. Connecting Cables

INFORMATION

Each E-509 sensor / servo-control module is calibrated with one particular piezo actuator. That piezo actuator must always be connected to that same controller channel. Labels on the rear panel of the device indicate the serial numbers of the piezo actuators that belong with each channel.

After the system has passed the electrical checks, the piezo actuators can be connected and the system can be operated. Follow these steps:

- 1. Switch the device OFF.
- 2. Connect the piezo actuators.

Each piezo actuator is equipped with cables for the piezo operating voltage and for the sensor, if present. Connect the first cable to the PZT output socket on the amplifier module and second with the sensor input socket on the piezo servo-controller.

If capacitive sensors are used, two sensor cables must be connected to the servocontroller. The cable labeled 'T' must be connected to the T socket (target signal) and the cable labeled 'P' to the P socket (probe signal).

4.6. Starting Operation

4.6.1. Analog Operation

INFORMATION

The external analog signal can be generated by a computer (e.g. from a data acquisition board). You can use the PI LabVIEW analog driver to generate the analog signal.

- > See the E500T0011 Technical Note for how to download the driver set from our website.
- 1. Turn all DC-OFFSET potentiometers CCW (zero offset).
- 2. Turn all SERVO switches to OFF (open-loop operation).
 - Position servo-controllers can be operated in closed-loop (SERVO=ON, control input is interpreted as target position) and open-loop (SERVO=OFF, control input determines the output voltage directly) modes.
 - In closed-loop mode, the servo-control circuit is active and compares the sensor signal with the target position. Hysteresis effects, nonlinearities and drift effects are eliminated.
 - In open-loop mode, the servo-control circuit is deactivated. The device works as a high-voltage amplifier. The input signal is amplified by the gain factor, and output to the piezo actuator. The output signal can also be offset manually with the DC-OFFSET potentiometer. In open-loop, the position sensor, if installed, is still active and the real-time position reading is correct.
- 3. Turn the power on.
 - The standard screen appears on the display. The current output voltages and displacements derived from the sensor signals are displayed for all channels. Because the controller is set to open-loop mode, the sensor reading is not fed back to control the position. If external forces act on the piezo actuator, its length will change accordingly and so will the sensor reading.
- 4. Switch the Servo switches to ON (closed-loop).
 - Now the displacement is controlled in closed-loop servo-mode. The display shows the current displacement values, as before.
- 5. Use the DC-Offset potentiometer to change the expansion.
- 6. Apply an external analog signal from 0 to +10 volts to control the expansion over the nominal range.
 - The expansion of the piezo actuator can be controlled either by the DC-OFFSET potentiometer or by an analog control input voltage applied to the CONTROL INPUT socket. In the latter case, the potentiometer setting is used as an offset to the control input voltage. This allows generation of unipolar output voltages from bipolar control voltages.
- 7. Watch the yellow overflow LED on the servo-module. If it lights up, the amplifier output is being clipped at one of its limits and the current displacement of the piezo actuator no longer complies with the control signal. Use the ZERO trim potentiometer to adjust the sensor reading window. Trim the potentiometer until the overflow LED stays dark.

4.6.2. Computer Controlled Operation

If an E-517 Interface/display unit is installed, remote control via TCP/IP, USB, RS-232 or IEEE-488 interface is possible. A comprehensive command set allows controlling any motion of the piezo actuator with maximum resolution (depending on the sensor installed).

See User Manual for the interface unit for details.

5. Module Description

5.1. E-500.00 19" Chassis with Power Supply

5.1.1. Specifications

| Model | E-500.00 |
|------------------------|--|
| Function | 19"-Chassis for Piezo Controller System: Amplifier Modules, Sensor- / Servo-Control Modules, Interface / Display Modules |
| Channels | 1, 2, 3 (up to 3 amplifier modules) |
| Dimensions | 450 x 132 x 296 mm + handles +feet |
| Operating Voltage | 100 - 240 V~, 50 - 60 Hz |
| Max. power consumption | 210 VA |
| Internal power supply | E530B0008 |

5.1.2. Dimensions

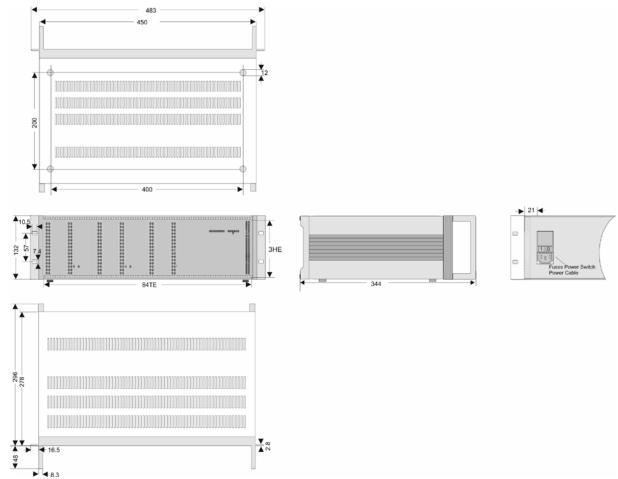


Fig. 3: E-500.00 chassis

5.2. E-501.00 9.5"Chassis with Power Supply

5.2.1. Specifications

| Model | E-501.00 |
|------------------------|---|
| Function | 9.5"-Chassis for Piezo Controller System: Amplifier Modules, Sensor- / Servo-Control Modules, Interface / Display Modules |
| Channels | 1, 3 (1 amplifier module) |
| Dimensions | 236 x 132 x 296 mm + handles + feet |
| Operating Voltage | 100 - 120 / 220 - 240 V~, 50 - 60 Hz |
| Max. power consumption | 90 VA |
| Internal power supply | E531B0005 |

5.2.2. Dimensions

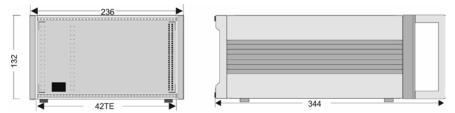


Fig. 4: E-501.00 chassis

5.3. E-503 3-Channel Piezo Amplifier

DANGER



High Voltage!

The E-503 amplifier can output up to 130 V. Touching this High Voltage can result in serious or even lethal injury due to electric shock.

- Only authorized and qualified personnel must install, operate, maintain and clean the E-503 amplifier.
- Operate a piezo actuator on a "PZT" socket only when it is connected to a protective earth conductor.

5.3.1. Front Panel Elements



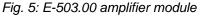




Fig. 6: E-503.00S amplifier module

| Labeling | Туре | Function |
|---------------------------|------------------------|--|
| POWER | LED | Amplifier state: |
| | Green/off | ■ Green: E-503 is ready for normal operation. |
| | | ■ Off: The E-500/E-501 system is switched off. |
| PZT -30 to 130 V | LEMO ERA.00.250.CTL | Output of the piezo voltage for the piezo actuator in the stage. Voltage in the range of -30 to 130 V. |
| E-503.00S only: PZT 100 V | LEMO ERA.00.250.CTL | Output of the piezo voltage for the piezo actuator in the stage. Fixed voltage of 100 V for piezo tip/tilt stages. |

| Labeling | Туре | Function |
|---------------------------|-----------------------|---|
| CONTROL INPUT -2 to +12 V | BNC | In analog operation, this control input voltage gives the target (either as voltage or position, depending on the servo mode). The input signal should always be in the range of 0 to 10 V (excursions to -2 or +12 V may cause overflow, especially with servo on, and reduce actuator lifetime). The control input range can be shifted using the "DC-OFFSET" potentiometer. The control input voltage can also be a computer-generated analog signal (e.g. from a DAQ board). You can use a PI LabVIEW Analog Driver set to generate that analog signal. See "Analog Operation" on p. 17 for details. |
| DC-OFFSET | 10-turn potentiometer | Adds 0 to 10 V to the "CONTROL INPUT" signal (only relevant in analog operation, see p. 17 for details) |

5.3.2. Operating Limits

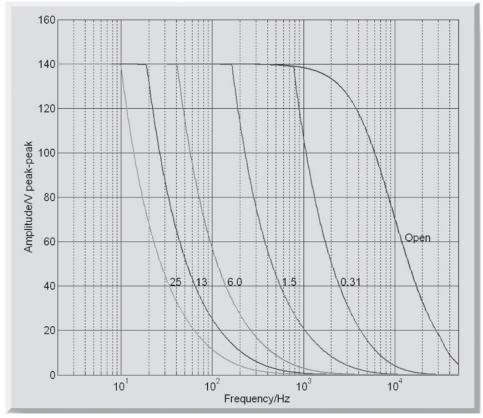


Fig. 7: E-503 operating limits with various piezo loads (open-loop), capacitance is measured in μF

5.3.3. Specifications

| | E-503.00 | E-503.00S |
|-------------------------------------|--|--|
| Function | Power amplifier | Power amplifier for tip/tilt systems |
| Channels | 3 | 3 |
| Amplifier | | |
| Control input voltage | -2 to 12 V | -2 to 12 V |
| | | Channel 3: no control input |
| Output voltage | -30 to 130 V | -30 to 130 V |
| | | Channel 3: 100 V fixed voltage |
| Peak current per channel, <10 ms | >140 mA (typical 180 mA) | >140 mA (typical 180 mA) |
| Average current per channel, >10 ms | >70 mA | >70 mA |
| Current limitation | Short-circuit-proof | Short-circuit-proof |
| Voltage gain | 10 ±0.1 | 10 ±0.1 (not with channel 3) |
| Input impedance | 100 kΩ / 1 nF | 100 kΩ / 1 nF (not with channel 3) |
| Interface and operation | | |
| Piezo connector | 3 × LEMO ERA.00.250.CTL | 3 × LEMO ERA.00.250.CTL |
| Analog input / control in | 3 × BNC | 2 × BNC |
| DC Offset | 3 x 10-turn pot., adds 0 to 10 V to Control In | 2 x 10-turn pot., adds 0 to 10 V to Control In |
| Miscellaneous | | |
| Operating temperature range | 5 to 50 °C | 5 to 50 °C |
| Overtemp protection | Deactivation at 85 °C | Deactivation at 85 °C |
| Dimensions | 14HP/3U | 14HP/3U |
| Mass | 0.9 kg | 0.9 kg |
| Operating voltage | E-500/E-501 system | E-500/E-501 system |
| Max. power consumption | < 40 W, limited by temperature | < 40 W, limited by temperature |

5.3.4. Pin Assignment

32-pin connector, DIN 41612, male

| Row | PIN a | PIN c |
|-----|----------------------------|---|
| 2 | Power Fail | OUT: ch1 (BNC+Offset) |
| 4 | IN: ch1 | OUT: ch1 (monitor of piezo voltage (PZT ÷100) |
| 6 | nc | nc |
| 8 | nc | nc |
| 10 | nc | OUT: ch2 (BNC+Offset) |
| 12 | IN: ch2 | OUT: ch2 (monitor of piezo voltage (PZT ÷100) |
| 14 | internal use Bus_A | internal use Bus_B |
| 16 | internal use Bus_Vcc | internal use Bus_GND |
| 18 | nc | OUT: ch3 (BNC+Offset)* |
| 20 | IN: ch3* | OUT: ch3 (monitor of piezo voltage (PZT ÷100) |
| 22 | GND (measurement) | GND (measurement) |
| 24 | GND | GND |
| 26 | IN: +24 V to +27 V | IN: +24 V to +27 V |
| 28 | IN:-37 V | OUT: -10 V |
| 30 | IN:+137 V | IN: +137 V |
| 32 | Protective earth (chassis) | Protective earth (chassis) |

^{*} E-503.00S: nc

5.4. E-504 High-Power Piezo Amplifier, Energy Recovery

DANGER



High Voltage!

The E-504 amplifier can output up to 130 V. Touching this High Voltage can result in serious or even lethal injury due to electric shock.

- Only authorized and qualified personnel must install, operate, maintain and clean the E-504 amplifier.
- Operate the piezo actuator on the "PZT" socket only when it is connected to a protective earth conductor.

5.4.1. Front Panel Elements



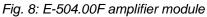




Fig. 9: E-504.00S amplifier module

| Labeling | Туре | Function |
|-----------------|---------------|---|
| POWER | LED | Amplifier state: |
| | Green/off | ■ Green: E-504 is ready for normal operation. |
| | | Off: The E-500/E-501 system is switched off. |
| E-504.00F only: | 10-turn | Adds 0 to 10 V to the "CONTROL INPUT" signal (only relevant |
| DC-OFFSET | potentiometer | in analog operation, see p. 17 for details) |
| E-504.00F only: | SMB | In analog operation, this control input voltage gives the target |
| CONTROL INPUT | | (either as voltage or position, depending on the servo mode). The input signal should always be in the range of 0 to 10 V |
| -2 to +12 V | | (excursions to -2 or +12 V may cause overflow, especially with servo on, and reduce actuator lifetime). |
| | | The control input range can be shifted using the "DC-OFFSET" potentiometer. |
| | | The control input voltage can also be a computer-generated analog signal (e.g. from a DAQ board). You can use a PI LabVIEW Analog Driver set to generate that analog signal. See "Analog Operation" on p. 17 for details. |

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| Labeling | Туре | Function |
|-----------------|----------------|--|
| E-504.00F only: | LEMO | Output of the piezo voltage for the piezo actuator in the stage. |
| PZT 🍂 | ERA.00.250.CTL | Voltage in the range of -30 to 130 V. |
| -30 to 130 V | | |
| E-504.00S only: | LEMO | Output of the piezo voltage for the piezo actuator in the stage. |
| PZT 🐴 | ERA.00.250.CTL | Fixed voltage of 100 V for piezo tip/tilt stages. |
| 100 V | | |

5.4.2. Operating Limits

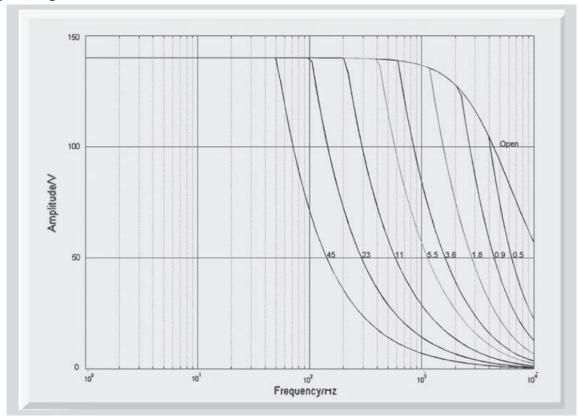


Fig. 10: E-504 operating limits with various piezo loads (open-loop), capacitance is measured in μF

5.4.3. Specifications

| | E-504.00F | E-504.00S |
|-----------------------------|---|---|
| Function | Power amplifier with energy recovery, 1 channel | Power amplifier with energy recovery, 1 channel, for tip/tilt systems |
| Amplifier | | |
| Control input voltage range | -2 to +12 V | - |
| Output voltage | -30 V to +130 V | 100 V |
| Peak output power < 5ms | 280 W | 280 W |
| Average output power | Equivalent to 100 W reactive power | Equivalent to 100 W reactive power |
| Peak output current < 5 ms | 2000 mA | 2000 mA |
| Average output current | 1000 mA | 1000 mA |
| Current limitation | Short-circuit-proof | Short-circuit-proof |
| Voltage gain | 10 ±0.1 | - |
| Ripple, noise | 5 mVrms / < 10 kHz, 20 mVpp / < 10 kHz | < 30 mVrms / < 100 kHz, < 100 mVpp / 100 kHz |
| | < 30mVrms / < 100 kHz, < 100mVpp / 100 kHz | < 150 mVpp / 20 MHz |
| | < 150mVpp / 20 MHz | |
| Base load (internal)* | 1.5 µF | 1.5 μF |
| | | |
| Output impedance | 1.5 μH / 0.5 Ω / 1.5 μF | 1.5 μH / 0.5 Ω / 1.5 μF |
| Amplifier step resolution | 10 mV | - |
| Amplifier type | Class D, switching amp (100 kHz) | Class D, switching amp (100 kHz) |
| Input impedance | 100 kΩ | - |
| Interfaces and operation | | |
| Piezo connector | LEMO ERA.00.250.CTL | LEMO ERA.00.250.CTL |
| Analog input | SMB | - |
| DC-Offset | 10-turn pot., adds 0 to +10 V to Control In | - |
| Miscellaneous | | |
| Operating temperature range | +5 to +50 °C | +5 to +50 °C |
| Dimensions | One 14T slot wide, 3H high | One 14T slot wide, 3H high |
| Mass | 0.9 kg | 0.9 kg |
| Operating voltage | E-500/E-501 system | E-500/E-501 system |
| Max. power consumption | < 30 W | < 30 W |

^{*} The internal base load is required to obtain a stable amplifier output voltage when no external piezo load is connected. The total load is the sum of internal base load and external piezo load. Note that the amplifier output power is allocated to the internal and external loads according to their capacitance values. This is of particular importance under large-signal conditions.

Examples: The small-signal capacitance of the connected piezo actuator is 550 nF, hence its large-signal capacitance is approx. 1.1 μ F (2 * 550 nF). Under large-signal conditions,

approx. 58 W will be allocated to the internal base load (1.5 μF), while approx. 42 W will be available for the external piezo load.

With a small-signal capacitance of 1 μ F, the piezo actuator would have a large-signal capacitance of 2 μ F, and approx. 57 W would be available for it.

5.4.4. Pin Assignment

32 pin connector, DIN 41612, male

| Row | PIN a | PIN c |
|-----|----------------------------|----------------------------|
| 2 | Power Fail | OUT: ch1 (SMB+Offset)* |
| 4 | IN: ch1* | OUT: ch1 (monitor) |
| 6 | Piezo voltage GND 🛕 | Piezo voltage GND 🗼 |
| 8 | OUT: piezo voltage 🔼 | OUT: piezo voltage 🔼 |
| 10 | n.c. | n.c. |
| 12 | n.c. | n.c. |
| 14 | IN: sync 200 kHz TTL | internal use, Bus_B |
| 16 | internal use, Bus_Vcc | internal use, Bus_GND |
| 18 | n.c. | n.c. |
| 20 | n.c. | n.c. |
| 22 | GND (measurement) | GND (measurement) |
| 24 | GND (power) | GND (power) |
| 26 | IN: +24 to +27 V | IN: +24 to +27 V |
| 28 | n.c. | n.c. |
| 30 | n.c. | n.c. |
| 32 | Protective earth (chassis) | Protective earth (chassis) |
| | | |

^{*} E-504.00S: Pins 2c and 4a are shorted.

5.5. E-505 High-Power Piezo Amplifier

DANGER



High Voltage!

The E-505 amplifier can output up to 130 V. Touching this High Voltage can result in serious or even lethal injury due to electric shock.

- Only authorized and qualified personnel must install, operate, maintain and clean the E-505 amplifier.
- Operate the piezo actuator on the "PZT" socket only when it is connected to a protective earth conductor.

5.5.1. Front Panel Elements



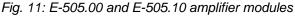




Fig. 12: E-505.00S amplifier module

| Labeling | Туре | Function |
|------------------------|---------------|--|
| POWER | LED | Amplifier state: |
| | Green/off | ■ Green: E-505 is ready for normal operation. |
| | | ■ Off: The E-500/E-501 system is switched off. |
| E-505.00 and .10 only: | 10-turn | Adds 0 to 10 V to the "CONTROL INPUT" signal (only relevant |
| DC-OFFSET | potentiometer | in analog operation, see p. 17 for details) |
| E-505.00 and .10 only: | BNC | In analog operation, this control input voltage gives the target |
| CONTROL INPUT | | (either as voltage or position, depending on the servo mode). |
| -2 to +12 V | | The input signal should always be in the range of 0 to 10 V (excursions to -2 or +12 V may cause overflow, especially with |
| | | servo on, and reduce actuator lifetime). |
| | | The control input range can be shifted using the "DC-OFFSET" potentiometer. |
| | | The control input voltage can also be a computer-generated |
| | | analog signal (e.g. from a DAQ board). You can use a PI |
| | | LabVIEW Analog Driver set to generate that analog signal. See "Analog Operation" on p. 17 for details. |

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| Labeling | Туре | Function |
|------------------------|----------------|--|
| E-505.00 and .10 only: | LEMO | Output of the piezo voltage for the piezo actuator in the stage. |
| PZT 🏂 | ERA.00.250.CTL | Voltage in the range of -30 to 130 V. |
| -30 to 130 V | | |
| E-505.00S only: | LEMO | Output of the piezo voltage for the piezo actuator in the stage. |
| PZT 🐴 | ERA.00.250.CTL | Fixed voltage of 100 V for piezo tip/tilt stages. |
| 100 V | | |

5.5.2. Operating Limits

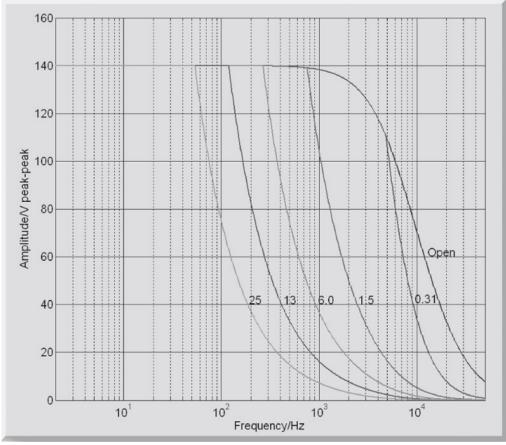


Fig. 13: E-505 operating limits with various piezo loads (open-loop), capacitance is measured in μF

5.5.3. Specifications

| | E-505.00 | E-505.10 | E-505.00S |
|-----------------------------|--|--|--------------------------------------|
| Function | Power amplifier | Power amplifier | Power amplifier for tip/tilt systems |
| Channels | 1 | 1 | 1 |
| Amplifier | | | |
| Control input voltage | -2 to +12 V | -2 to +12 V | - |
| Output voltage | -30 to +130 V | -30 to +130 V | 100 V |
| Peak current | 2 A (<3 ms) | 10 A (<200 μs) | 2 A (<3 ms) |
| Average current | 250 mA | 250 mA | 250 mA |
| Current limitation | Short-circuit-proof | Short-circuit-proof | Short-circuit-proof |
| Noise, 0 to 100 kHz | <0.6 mVrms | <1.0 mVrms | <0.6 mVrms |
| Voltage gain | 10 ±0.1 | 10 ±0.1 | - |
| Input impedance | 1 MΩ / 1 nF | 1 MΩ / 1 nF | - |
| Interface and operation | | | |
| Piezo connector | LEMO ERA.00.250.CTL | LEMO ERA.00.250.CTL | LEMO ERA.00.250.CTL |
| Analog input | BNC | BNC | - |
| DC Offset | 10-turn pot., adds 0 to 10 V to Control In | 10-turn pot., adds 0 to 10 V to Control In | - |
| Miscellaneous | | | |
| Operating temperature range | +5 to +50 °C | +5 to +50 °C | +5 to +50 °C |
| Overtemp protection | Deactivation at +85°C | Deactivation at +85°C | Deactivation at +85°C |
| Dimensions | 14HP/3U | 14HP/3U | 14HP/3U |
| Ground | 0.9 kg | 0.9 kg | 0.9 kg |
| Operating voltage | E-500/E-501 system | E-500/E-501 system | E-500/E-501 system |
| Max. power consumptions | 55 W | 55 W | 55 W |

5.5.4. Pin Assignment

32 pin connector, DIN 41612, male

| Row | PIN a | PIN c |
|-----|----------------------------|----------------------------|
| 2 | Power Fail | OUT: ch1 (BNC+Offset)* |
| 4 | IN: ch1* | OUT: ch1 (monitor) |
| 6 | Piezo voltage GND | Piezo voltage GND 🔥 |
| 8 | OUT: piezo voltage 🔼 | OUT: piezo voltage 🔼 |
| 10 | n.c. | n.c. |
| 12 | n.c. | n.c. |
| 14 | internal use,Bus_A | internal use, Bus_B |
| 16 | internal use, Bus_Vcc | internal use, Bus_GND |
| 18 | n.c. | n.c. |
| 20 | n.c. | n.c. |
| 22 | GND (measurement) | GND (measurement) |
| 24 | GND (power) | GND (power) |
| 26 | IN: +24 V to +27V | IN: +24 V to +27 V |
| 28 | IN: -37 V | OUT: -10 V |
| 30 | IN: +137 V | IN: +137 V |
| 32 | Protective earth (chassis) | Protective earth (chassis) |
| | | |

^{*} E-505.00S: Pins 2c and 4a are shorted.

5.6. E-506 Linearized Piezo Amplifier, Charge Control

DANGER



High Voltage!

The E-506 amplifier can output up to 130 V. Touching this High Voltage can result in serious or even lethal injury due to electric shock.

- Only authorized and qualified personnel must install, operate, maintain and clean the E-506 amplifier.
- Operate the piezo actuator on the "PZT" socket only when it is connected to a protective earth conductor.

INFORMATION

Standard nanopositioning stages are not suitable for operation with the E-506.10 and cannot be connected via an adapter!

See the E506T0002 Technical Note for a more detailed description of the E-506.10 charge-controlled amplifier module. **Front Panel Elements**



Fig. 14: E-506.10 amplifier module

| Labeling | Туре | Function |
|-----------|--------------------------|--|
| POWER | LED | Amplifier state: |
| | Green/off | ■ Green: E-506 is ready for normal operation. |
| | | ■ Off: The E-500/E-501 system is switched off. |
| OVERTEMP | LED | Overtemp state: |
| | Red/off | Red: Piezo voltage output is deactivated due to overtemp condition at the piezo actuator (see below) |
| | | Off: No overtemp condition |
| DC-OFFSET | 10-turn potentiometer | Adds 0 to 10 V to the "CONTROL INPUT" signal (only relevant in analog operation, see p. 17 for details) |

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| Labeling | Туре | Function |
|------------------------------|---|--|
| CONTROL INPUT -2 to +12 V | BNC | In analog operation, this control input voltage gives the target (either as voltage or position, depending on the servo mode). The input signal should always be in the range of 0 to 10 V (excursions to -2 or +12 V may cause overflow, especially with servo on, and reduce actuator lifetime). The control input range can be shifted using the "DC-OFFSET" potentiometer. The control input voltage can also be a computer-generated analog signal (e.g. from a DAQ board). You can use a PI LabVIEW Analog Driver set to generate that analog signal. See "Analog Operation" on p. 17 for details. |
| TEMP SENSOR | LEMO EPL.0S.303.HLN | Connection for PT1000 temperature sensor or dummy plug. Pinout on p. 35 |
| PZT 4 -30 to +130 V | LEMO EGG.0B.302.CLL Pinout on p. 35 | Output of the piezo voltage for the piezo actuator in the stage. Piezo voltage output is deactivated if a temperature of 150 °C is exceeded at the piezo actuator. Automatic reactivation at a temperature < 146 °C |

5.6.2. Operating Limits

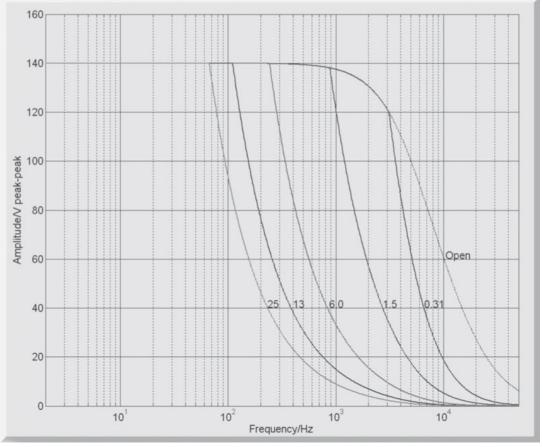


Fig. 15: E-506 operating limits with various piezo loads (open-loop), capacitance is measured in μF . The minimum capacitive load is 0.3 μF

5.6.3. Specifications

| | E-506.10 | Tolerance |
|------------------------------------|---|-----------|
| Function | Linearized amplifier module, charge-controlled | |
| Channels | 1 | |
| Amplifier | | |
| Input voltage | -2 to +12 V | |
| Output voltage* | -30 to 130 V | |
| Peak output power, < 2.5 ms | 280 W | max. |
| Average output power | 30 W | max. |
| Peak current, < 2.5 ms | 2 A | |
| Average current | 250 mA | |
| Current limitation | Short-circuit-proof | |
| Ripple, noise 0 to 100 kHz | <0.6 mVrms | |
| Reference capacitance (adjustable) | 1 to 280 μF | |
| Input impedance | 1 MΩ / 1 nF | |
| Interfaces and operation | | |
| Piezo connector (voltage output) | LEMO 2-pin EGG.0B.302.CLL | |
| Analog input | BNC | |
| Display | LEDs for power and piezo overtemp | |
| DC Offset | 10-turn pot., adds 0 to 10 V to Control In | |
| Piezo temperature sensor (input) | PT 1000; | |
| | LEMO socket; deactivation of the piezo voltage output at 150 °C | |
| Miscellaneous | | |
| Operating temperature range | +5 to +50 °C | |
| Dimensions | 14HP/3U | |
| Mass | 0.9 kg | |
| Operating voltage | E-500/E-501 system | |
| Power consumption | 55 W | max. |

^{*}Max. 85°C, deactivation of the piezo voltage output (internal overtemp protection)

Minimum frequencies* for charge-controlled operation:

| Capacitance (piezo actuator) | f _{trans} |
|------------------------------|--------------------|
| 0.33 µF | 250 mHz |
| 1.06 µF | 80 mHz |
| 6.2 µF | 9 mHz |
| 14 μF | 4 mHz |

^{*} Voltage-controlled operation for lower frequencies

5.6.4. Pin Assignment

PZT High Voltage

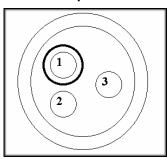


Top pin: Plus

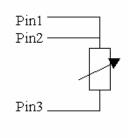
Bottom pin: Return conductor (minus; the actuator connected must have a floating-ground construction!)

Housing: Protective earth

PT1000 Temperature sensor



LEMO EPL.OS.303.HLN Temperature sensor socket



Schematic circuit diagram of temperature sensor

Pin 1: Temp_SA Pin 2: Temp_S Pin 3: GND/PE

Housing: Protective earth conductor/GND/PE

32 pin connector, DIN 41612, male

| Row | PIN a | PIN c |
|-----|----------------------------|----------------------------|
| 2 | Power Fail | OUT: ch1 (BNC+Offset) |
| 4 | IN: ch1 | OUT: ch1 (monitor) |
| 6 | Piezo voltage GND 🗼 | Piezo voltage GND 🗼 |
| 8 | OUT: piezo voltage 🔼 | OUT: piezo voltage 🔼 |
| 10 | n.c. | n.c. |
| 12 | n.c. | n.c. |
| 14 | n.c. | n.c. |
| 16 | IN: -15 V | n.c. |
| 18 | n.c. | n.c. |
| 20 | n.c. | n.c. |
| 22 | GND (measurement) | GND (measurement) |
| 24 | GND (power) | GND (power) |
| 26 | IN:+24 V to +27 V | IN: +24 V to +27 V |
| 28 | IN: -37 V | OUT: -10 V |
| 30 | IN: +137 V | IN: +137 V |
| 32 | Protective earth (chassis) | Protective earth (chassis) |

5.7. E-508 High-Power Piezo Amplifier with 1100 V Output Voltage

DANGER



High Voltage!

The E-508 amplifier can output up to 1100 V. Touching this High Voltage can result in serious or even lethal injury due to electric shock.

- Only authorized and qualified personnel must install, operate, maintain and clean the E-508 amplifier.
- Operate the piezo actuator on the "PZT HIGH VOLTAGE" socket only when it is connected to a protective earth conductor.

5.7.1. Front Panel Elements



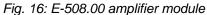




Fig. 17: E-508.OE amplifier module

| Labeling | Туре | Function | |
|-----------------------------|-----------------------|---|--|
| POWER | LED | Amplifier state: | |
| | Green/off | Green: E-508 is ready for normal operation. Off: The E-500/E-501 system is switched off. | |
| E-508.00 only: DC-OFFSET | 10-turn potentiometer | Adds 0 to 10 V to the "CONTROL INPUT" signal (only relevant in analog operation, see p. 17 for details) | |

| Labeling | Туре | Function |
|---------------|--------------------------------|---|
| CONTROL INPUT | E-508.00: BNC E-508.OE: SMB | In analog operation, this control input voltage gives the target (either as voltage or position, depending on the servo mode). Input voltage range: |
| | | ■ Servo off: ±1/100 of selected output range |
| | | Servo on: 0 to 10 V |
| | | With E-508.00, the control input range can be shifted using the "DC-OFFSET" potentiometer. The control input voltage can also be a computer-generated analog signal (e.g. from a DAQ board). You can use a PI LabVIEW Analog Driver set to generate that analog signal. See "Analog Operation" on p. 17 for details. |
| | | See the "Specifications" table below for the input voltage range. |
| A | LEMO | Output of the piezo voltage for the piezo actuator in the stage. |
| PZT Z Z | EGG.0B.701.CJL.1173 | See the "Specifications" table below for the output voltage |
| High Voltage | Pinout on p. 39 | range. |

5.7.2. Operating Limits

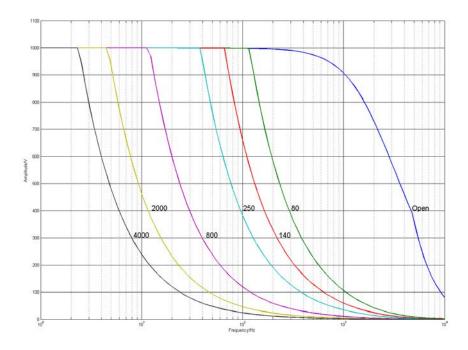


Fig. 18: E-508 operating limits with various piezo loads (open-loop), capacitance is measured in nF

5.7.3. Specifications

| | E-508.00 | E-508.OE | Unit |
|-----------------------------------|--|--|------------|
| Function | Power amplifier for PICA high- voltage piezos | Power amplifier for PICA high- voltage piezos | |
| Amplifier | | | |
| Output voltage | 3 to + 1100 (Standard) | 3 to + 1100 (Standard) | V |
| | (-260 to + 780 | (-260 to + 780 | |
| | - 550 to + 550 | - 550 to + 550 | |
| | +260 to -780 | +260 to -780 | |
| | - 3 to - 1100) (jumper- selectable) | - 3 to - 1100) (factory- settable) | |
| Amplifier channels | 1 | 1 | |
| Average output power | 13 | 18 | W |
| Peak output power, < 5 ms | 50 | 400 | W |
| Average current | 12 | 18 | mA |
| Peak current, < 5ms | 50 | 400 | mA |
| Amplifier bandwidth, small signal | 6 | 10 | kHz |
| Amplifier bandwidth, large signal | 50 (200 nF) | 70 (200 nF) | Hz |
| Ripple, noise | 5 | 20 | mV_{RMS} |
| 0 to 100 kHz | 50 (100 nF) | 200 (100 nF) | mV_{P-P} |
| Current limitation | Short-circuit-proof | Short-circuit-proof | |
| Voltage gain | +100 ±1, -100 ±1 (selectable) | +100 ±1, -100 ±1 (selectable) | |
| Control input voltage | Servo off: ±1/100 of selected output range | Servo off: ±1/100 of selected output range | |
| | Servo on: 0 to 10 V | Servo on: 0 to 10 V | |
| Input impedance | 100 | 100 | kΩ |
| Interfaces and operation | | | |
| Piezo voltage output | LEMO EGG.0B.701.CJL.1173 | LEMO EGG.0B.701.CJL.1173 | |
| Input | BNC | SMB | |
| DC-Offset | 10-turn pot., adds 0 to 10 V to Control In | - | |
| Miscellaneous | | | |
| Operating voltage | E-500/E-501 system | E-500/E-501 system | |
| Operating temperature range | +5 °C to +50 °C output power 10 % derated over 40 °C) | +5 °C to +50 °C (output power 10 % derated over 40 °C) | °C |
| Mass | 0.75 | 0.75 | kg |
| Dimensions | 14 HP/3 U | 14 HP/3 U | |

5.7.4. High-Voltage Actuator Types and Terminology

If you order the actuator and controller together, and/or provide PI with sufficient information about your application, then the actuator connector, output voltage range and gain polarity will be set up as required.

If you are connecting other actuators or wiring your own connector, read the discussion of actuator type carefully and any documentation that came with the actuator.

Bipolar Actuators

Here the output voltage swing is so chosen that the actuator sees both negative and positive high voltages. The output always has one lead at 0 V, and here the other is in a zero-crossing range, commonly ±500 · V.

Unipolar Actuators

The notation of "positive" and "negative" polarity of piezo actuators does not refer to their direction of motion. Unipolar piezos of any polarity will elongate when a higher voltage is applied to their (+) than to their (-) terminal.

"Positive" and "negative" refers to the sign of the voltage on the core of the cable.

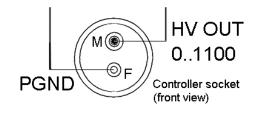
All standard PI piezo actuators with 2-conductor LEMO connectors have positive polarity.

5.7.5. Pin Assignment

PZT High Voltage

Type: LEMO EGG.0B.701.CJL.1173

HV OUT: High-voltage output
PGND: Power ground
Housing: Cable shield



32-pin connector, DIN 41612, male

| Row | PIN a | PIN c |
|-----|----------------------------|---|
| 2 | IN: Power Fail* | OUT: control (E-508.00: BNC+Offset / E-508.0E: SMB) |
| 4 | IN: control | OUT: monitor of piezo voltage (PZT ÷1000) |
| 6 | nc | nc |
| 8 | nc | nc |
| 10 | nc | nc |
| 12 | nc | nc |
| 14 | internal use (Bus_A)* | internal use (Bus_B)* |
| 16 | internal use (Bus_Vcc)* | internal use (Bus_GND)* |
| 18 | nc | nc |
| 20 | nc | nc |
| 22 | GND (measurement) | GND (measurement) |
| 24 | GND | GND |
| 26 | IN: +24 V to +27 V | IN: +24 V to +27 V |
| 28 | nc | nc |
| 30 | nc | nc |
| 32 | Protective earth (chassis) | Protective earth (chassis) |

^{*} no connection on E-508.OE

5.7.6. E-508.00 Gain Polarity and Output Range Settings

NOTICE



Damage from electrostatics!

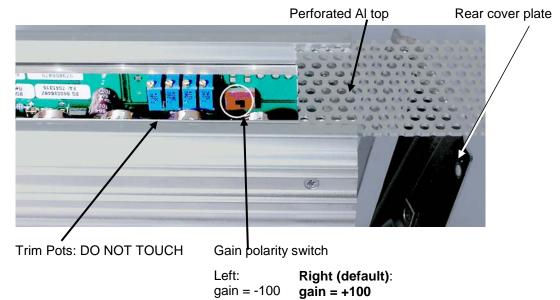
The E-500/E-501 system contains electrostatic sensitive devices (EGB) and can be damaged if handled improperly.

- > Avoid touching components, pins and PCB tracks.
- Before touching an electronic component, discharge yourself of any electric charges:
 - While working, wear an antistatic wrist strap or
 - Briefly touch a conducting, grounded object.

Making the gain polarity switch and output range jumper accessible

Only remove modules from the chassis when you are authorized and have the corresponding qualifications.

- 1. Remove the E-500/E-501 system from the power source by pulling the power plug.
- 2. Wait a minute to be sure that any residual voltage has dissipated.
- 3. Remove the E-508.00 module from the chassis:
 - a) Loosen the four Phillips screws on the front panel.
 - b) Using the grip at the bottom of the front panel, pull the module out of the chassis.
- 4. To access settings for gain polarity and output range, remove the rear cover plate from the E-508.00 module and slide back the perforated aluminum top.



Setting the Gain Polarity Switch

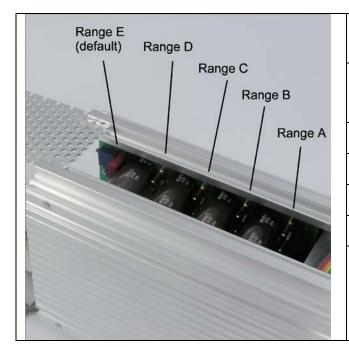
It is important to understand the relation between gain and the Control In range.

With DC-offset = 0 (full CCW), the Control In range is equal to output range (as set below) divided by the gain.

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For example, in open-loop operation, the output range +3 to +1100 V and gain +100 yield a Control In range of 0 to +11 V.

Setting the Output Range Jumper



| Ranges | |
|--------|------------------------------------|
| E | +3 to +1100 V (factory setting) |
| D | -260 to +780 V |
| С | -550 to +550 V |
| В | -780 to +260 V |
| A | -1100 to -3 V |
| | |

To change setting, remove red cap (shown in Range E position) and replace over pins corresponding to desired range.

5.8. E-509 Signal Conditioner / Servo-Controller Module

INFORMATION

- See the E-509 User Manual (PZ77) for a detailed description.
- See also the User Manuals for the E-802 servo-controller submodule (with all E-509 versions) and the E-801 sensor submodule (only with LVDT and strain gauge sensor versions).

5.8.1. Front Panel Elements of Modules for Dual-Electrode Capacitive Sensors



Fig. 19: E-509.C1A sensor / servo controller



Fig. 20: E-509.C2A sensor / servo controller



Fig. 21: E-509.C3A sensor / servo controller

| Labeling | Туре | Function |
|----------|--------------------|---|
| Т | LEMO | Input for the Target sensor signal from the piezo stage. |
| | EPL.00.250.NTD | |
| Р | LEMO | Input for the Probe sensor signal from the piezo stage. |
| | EPL.00.250.NTD | |
| ZERO | Trim potentiometer | A trimmer adjustment tool can be used on the ZERO potentiometer for a zero-point adjustment of the sensor. A zero-point adjustment can be necessary after longer operation (changes in temperature) or if the load on the piezo stage is changed. |
| OFL | LED Yellow/off | Overflow state: Yellow: Overflow condition, i.e. the amplifier is near its range limit. Off: No overflow condition When the OFL LED comes on, a zero-point adjustment of the sensor can be necessary. See p. 17 and the E-509 User Manual (PZ77E) for details. |

| Labeling | Туре | Function |
|------------------|----------------|---|
| SERVO x ON/OFF | Toggle switch | Switch for the servo mode selection of the corresponding channel: |
| x stands for the | | ON: Servo mode is switched on (closed-loop operation) |
| channel number | | ■ OFF: Servo mode is switched off (open-loop operation) |
| | | See also "Starting Operation" on p. 17. |
| SENSOR | LEMO | Output of the monitor signal(s) for the sensor channel(s). |
| MONITOR | EGG.0B.306.CLL | Pinout on p. 48. |

5.8.2. Front Panel Elements of Modules for PISeca Single-Electrode Capacitive Sensors



Fig. 22: E-509.E3 sensor / servo controller

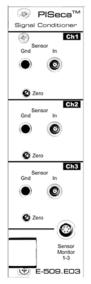


Fig. 23: E-509.E03 sensor signal conditioner

| Labeling | Туре | Function |
|--|--|---|
| Gnd | Banana socket | Ground connection for target plane of the PISeca single-electrode capacitive sensor. |
| In | LEMO ECP.00.650.NLL. 543, triaxial | Input for the Probe sensor signal of the PISeca single-electrode capacitive sensor. |
| With E-509.E3 only: | Toggle switch | Switch for the servo mode selection of the corresponding channel: |
| Servo x On/Off x stands for the channel number | | ON: Servo mode is switched on (closed-loop operation) OFF: Servo mode is switched off (open-loop operation) See also "Starting Operation" on p. 17. |

| Labeling | Туре | Function |
|--------------------|------------------------|---|
| With E-509.E3 ony: | LED | Overflow state: |
| OFL | Yellow/off | Yellow: Overflow condition, i.e. the amplifier is near its range limit. |
| | | Off: No overflow condition When the OFL LED comes on, a zero-point adjustment of the sensor can be necessary. See p. 17 and the E-509 User Manual (PZ77E) for details. |
| ZERO | Trim potentiometer | A trimmer adjustment tool can be used on the ZERO potentiometer for a zero-point adjustment of the sensor. A zero-point adjustment can be necessary after longer operation (changes in temperature) or if the load on the piezo stage is changed. |
| SENSOR MONITOR | LEMO EGG.0B.306.CLL | Output of the monitor signals for the sensor channels. Pinout on p. 48. |

5.8.3. Front Panel Elements of Modules for Strain Gauge Sensors



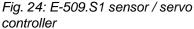




Fig. 25: E-509.S3 and E-509.S31 sensor / servo controller

INFORMATION

In the labeling of E-509.S1 and E-509.S3 modules, X stands for S.

INFORMATION

E-509.S31 and E-509.S3N models for use with P-611 NanoCube® stages:

E-509.S31 differs from E-509.S3 only in the settings of the internal E-801 sensor submodule. E-509.S3N consists of an E-509.S31 module plus a P-611.91 3-channel adapter cable LEMO/Sub-D 25 (f).

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| Labeling | Туре | Function |
|----------------------|--------------------|---|
| OFL | LED | Overflow state: |
| | Yellow/off | Yellow: Overflow condition, i.e. the amplifier is near its range limit. |
| | | Off: No overflow condition |
| | | When the OFL LED comes on, a zero-point adjustment of the sensor can be necessary. See p. 17 and the E-509 User Manual (PZ77E) for details. |
| SERVO ON/OFF | Toggle switch | Switch for the servo mode selection of the corresponding channel: |
| 1, 2 and 3 stand for | | ON: Servo mode is switched on (closed-loop operation) |
| the channel numbers | | OFF: Servo mode is switched off (open-loop operation) |
| numbers | | See also "Starting Operation" on p. 17. |
| ZERO | Trim potentiometer | A trimmer adjustment tool can be used on the ZERO potentiometer for a zero-point adjustment of the sensor. A zero-point adjustment can be necessary after longer operation (changes in temperature) or if the load on the piezo stage is changed. |
| SENSOR | LEMO | Input for the signals of the strain gauge sensor of the piezo stage. |
| | ERA.0S.304.CLL | Pin assignment on p. 47. |
| SENSOR | E-509.S1: | Output of the monitor signal(s) for the sensor channel(s). |
| MONITOR | BNC | Pin assignment for E-509.S3 on p. 48. |
| | E-509.S3: | |
| | LEMO | |
| | ERA.0S.303.CLL | |

5.8.4. Specifications

| | E-509.C1A / E-509.C2A / E-509.C3A | E-509.S1 / E-509.S3 / E-509.S31 |
|-----------------------|---|---|
| Function | Signal conditioner and servo- controller for piezo mechanics | Signal conditioner and servo- controller for piezo mechanics |
| Channels | 1/2/3 | 1/3 |
| Sensor | | |
| Servo characteristics | Analog proportional-integral (P-I) algorithm with notch filter | Analog proportional-integral (P-I) algorithm with notch filter |
| Sensor type | 2-plate capacitive | SGS |
| Sensor channels | 1 / 2 /3 | 1/3 |
| Sensor bandwidth | 0.3 to 3 kHz (adjustable with jumper); up to 10 kHz on request | 0.3; 1; 3 kHz |
| Noise factor | 0.115 ppm/Hz ^{1/2} | - |
| Thermal drift | < 0.3 mV/C° | < 3 mV /C° |
| Linearity | <0.05% | <0.2% |
| Linearization | ILS (Integrated Linearization System) | On E-801 submodule |

| | E-509.C1A / E-509.C2A / E-509.C3A | E-509.S1 / E-509.S3 / E-509.S31 | |
|-----------------------------|-----------------------------------|---|--|
| Interfaces and operation | | | |
| Sensor connection | LEMO EPL.00.250.NTD | LEMO ERA.0S.304.CLL | |
| Sensor monitor output | 0 to 10 V (±5 V) | 0 to 10 V (±5 V) | |
| Sensor monitor socket | LEMO 6-pin FGG.0B.306.CLAD56 | BNC (1-ch.) / 3-pin. LEMO ERA.0S.303.CLL (3-ch.) | |
| Display | Overflow LED | Overflow LED | |
| Miscellaneous | | | |
| Operating temperature range | +5 to +50°C | +5 to +50°C | |
| Dimensions | 7HP/3U | 7HP/3U | |
| Mass | 0.2 kg / 0.25 kg / 0.35 kg | 0.2 kg / 0.25 kg / 0.35 kg | |
| Operating voltage | E-500/E-501 system, +/-15 V/0.5 A | E-500/E-501 system, +/-15 V/0.5 A | |
| Max. power consumption | 4 to 8 W | 4 to 8 W | |

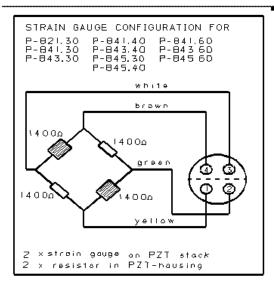
| | E-509.E03 | E-509.E3 |
|--------------------------------------|---|--|
| Function | Signal conditioner electronics for PISeca sensors | Sensor / Piezo Servo-Control Module for PISeca sensors |
| Channels | 3 | 3 |
| Sensor | | |
| Servo characteristics | - | Analog proportional-integral (P-I) algorithm with notch filter |
| Sensor type | PISeca single-electrode, capacitive | PISeca single-electrode, capacitive |
| Sensor bandwidth | 3 kHz | 3 kHz |
| | 0.3 / 10 kHz (selectable) | 0.3 / 10 kHz (selectable) |
| Measurement range extension factors* | 2 / 2.5 / 5 (option) | 2 / 2.5 / 5 (option) |
| Synchronization | 3 synchronized channels | 3 synchronized channels |
| Electrical properties | | |
| Output voltage | 0 to 10 V | 0 to 10 V |
| | -5 to +5 V, -10 to 0 V (selectable) | |
| Thermal drift | <1 mV / C° | <1 mV / C° |
| Resolution @ 300 Hz (RMS) | <0.001% of measurement range | <0.001% of measurement range |
| Resolution @ 3 kHz (RMS) | <0.0025% of measurement range | <0.0025% of measurement range |
| Linearity @ nominal range | <0.1 % (<0.2% for D-510.020) | <0.1 % (<0.2% for D-510.020) |
| Interfaces and operation | | |
| Sensor connection | 3 x LEMO ECP.00.650.NLL.543 socket, triaxial | 3 x LEMO ECP.00.650.NLL.543 socket, triaxial |
| Sensor monitor | 0 to 10 V (±5 V) | 0 to 10 V (±5 V) |
| Sensor monitor socket | LEMO 6-pin FGG.0B.306.CLAD56 | LEMO 6-pin FGG.0B.306.CLAD56 |
| Display | _ | 3 × Overflow LED |
| Supported functionality | ILS (Integrated Linearization System) | ILS (Integrated Linearization System) |

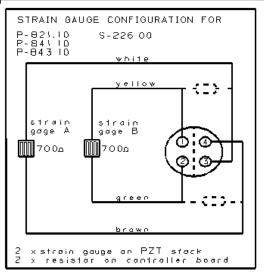
| | E-509.E03 | E-509.E3 |
|-----------------------------|--------------------|--------------------|
| Miscellaneous | | |
| Operating temperature range | +5°C to +40 °C | +5°C to +40 °C |
| Dimensions | 7HP/3U | 7HP/3U |
| Target ground connector | 3 x banana socket | 3 x banana socket |
| Operating voltage | E-500/E-501 system | E-500/E-501 system |

^{*}Extension factors to multiply by the nominal measurement range of the selected sensor head D-510, to be specified with order

5.8.5. Pin Assignment

SENSOR socket of E-509.S3 and E-509.S1





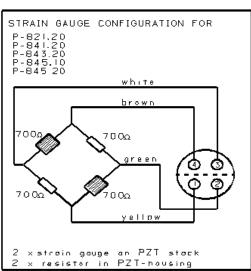


Fig. 26: Strain gauge sensor wiring for various piezo actuators

SENSOR MONITOR socket of E-509.S3

LEMO socket ERA.0S.303.CLL

The SENSOR MONITOR socket carries the signals from all three channels.

Each E-509.S3 comes with the E-808.90 sensormonitor cable. The purpose of this cable is simply to split up the signals of the SENSOR MONITOR socket for the three channels.

The leads of this open-ended cable are color coded:

white = channel 1,

brown = channel 2,

green = channel 3,

shield = GND.



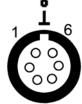
Fig. 27: Three-pin LEMO sensor monitor socket

SENSOR MONITOR socket of E-509.CxA and E-509.Ex

LEMO socket (FGG.0B.306.CLAD56), 6-pin

| pin 1 | ch1+ |
|---------|------|
| pin 2 | ch1- |
| pin 3 | ch2+ |
| pin 4 | ch2- |
| pin 5 | ch3+ |
| pin 6 | ch3- |
| shield: | GND |

Fig. 28 Six-pin LEMO sensor monitor socket



Each capacitive sensor version comes with the D-893.32 sensor monitor cable (2 m). The purpose of this cable is simply to split up the signals of the SENSOR MONITOR socket onto three separate BNC connectors. The BNC connectors are each labeled with the channel number.

E-509.S3 32-pin connector, DIN 41612, male

| Pin No. | Function | Pin No. | Function |
|---------|------------------------|---------|------------------------|
| 2a | GND | 2c | GND |
| 4a | internal use | 4c | OUT: ch1 (control) |
| 6a | IN: +15 V | 6c | IN: +15 V |
| 8a | IN: -15 V | 8c | IN: -15 V |
| 10a | internal use* | 10c | internal use |
| 12a | internal use (Bus_A) | 12c | OUT: ch2 (control) |
| 14a | OUT: Display ch2 | 14c | OUT: Display ch1 |
| 16a | internal use (Bus_B) | 16c | OUT: Display ch3 |
| 18a | internal use (BUS_Vcc) | 18c | internal use (BUS_GND) |
| 20a | IN: Control ch1 | 20c | OUT: ch3 (control) |
| 22a | IN: Control ch3* | 22c | IN: Control ch2 |
| 24a | internal use | 24c | internal use |
| 26a | IN: VC/EC ch2 | 26c | IN: VC/EC ch1 |
| 28a | OUT: Overflow ch1 | 28c | IN: VC/EC ch3* |
| 30a | OUT: Overflow ch3 | 30c | OUT: Overflow ch2 |
| 32a | nc | 32c | nc |

Note: Pins labeled with "nc" may be used internally and must not be connected externally.

E-509.S1 32-pin connector, DIN 41612, male

| Pin No. | Function | Pin No. | Function |
|---------|------------------------|---------|------------------------|
| 2a | GND | 2c | GND |
| 4a | internal use | 4c | OUT: ch1 (control) |
| 6a | IN: +15 V | 6c | IN: +15 V |
| 8a | IN: -15 V | 8c | IN: -15 V |
| 10a | internal use | 10c | internal use |
| 12a | internal use (Bus_A) | 12c | nc |
| 14a | nc | 14c | OUT: Display ch1 |
| 16a | internal use (Bus_B) | 16c | nc |
| 18a | internal use (BUS_Vcc) | 18c | internal use (BUS_GND) |
| 20a | IN: Control ch1 | 20c | nc |
| 22a | nc | 22c | nc |
| 24a | internal use | 24c | internal use |
| 26a | nc | 26c | IN: VC/EC ch1 |
| 28a | OUT: Overflow ch1 | 28c | nc |
| 30a | nc | 30c | nc |
| 32a | nc | 32c | nc |

Note: Pins labeled with "nc" may be used internally and must not be connected externally.

E-509.C1A, E-509.C2A, E-509.C3A, E-509.E3, E-509.E03 32-pin connector, DIN 41612, male

| Pin No. | Func | Function on Pin | | Pin No. | Function on | | |
|---------|--------------------------|--------------------|------|---------|---------------------------|--------------------|------|
| | .C3A, .Ex** | .C2A | .C1A | | .C3A, Ex** | .C2A | .C1A |
| 2a | GND | * | * | 2c | GND | * | * |
| 4a | n.c. | * | * | 4c | Control signal output CH1 | * | * |
| 6a | + 15 V | * | * | 6c | + 15 V | * | * |
| 8a | - 15 V | * | * | 8c | - 15 V | * | * |
| 10a | n.c. | * | * | 10c | n.c. | * | * |
| 12a | internal use | * | * | 12c | Control signal output CH2 | * | n.c. |
| 14a | Display CH2 | * | n.c. | 14c | Display CH1 | * | * |
| 16a | internal use | * | n.c. | 16c | Display CH3 | n.c. | n.c. |
| 18a | internal use | n.c. | n.c. | 18c | internal use | * | * |
| 20a | Control signal input CH1 | * | * | 20c | Control signal output CH3 | to JP210, pin 1 | n.c. |
| 22a | Control signal input CH3 | to JP210, pin 2 | n.c. | 22c | Control signal input CH2 | * | n.c. |
| 24a | n.c. | * | * | 24c | SYNC | * | * |
| 26a | Servo ON/OFF, ch2 | * | n.c. | 26c | Servo ON/OFF, ch1 | * | * |
| 28a | overflow CH1 | * | * | 28c | Servo ON/OFF, ch3 | n.c. | n.c. |
| 30a | overflow CH3 | n.c. | n.c. | 30c | overflow CH2 | * | n.c. |
| 32a | n.c. | * | * | 32c | n.c. | * | * |

^{*} Same as on E-509.C3A

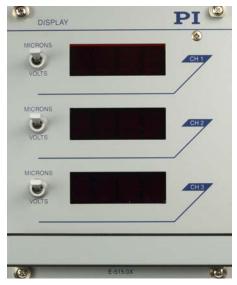
JP210 shorted on E-509.C2A (default): connects CH3 input to CH3 output (i.e. CH3 bypassed)

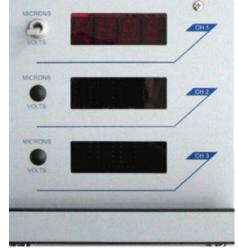
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^{**} E-509.E03 has no servo-controller and hence all servo-related pins are not connected n.c.: No Connection: may be used on the backplane and must not be connected.

5.9. E-515 Display Modules

5.9.1. Front Panel Elements





DISPLAY

Fig. 29: E-515.03 display module

Fig. 30: E-515.01 display module

INFORMATION

In the labeling of E-515.01 and E-515.03 display modules, *X* stands for the supported number of channels.

| Labeling | Туре | Function |
|-----------|-------------------------|---|
| MICRONS / | Toggle switch | Switch for selection of the signal to be displayed for the channel: |
| VOLTS | | ■ MICRONS: Position (displacement) measured by the sensor |
| | | ■ VOLTS: Piezo voltage as output by the amplifier |
| - | Display with 3 ½ digits | If adjustment of the display should be necessary, see p. 52. |

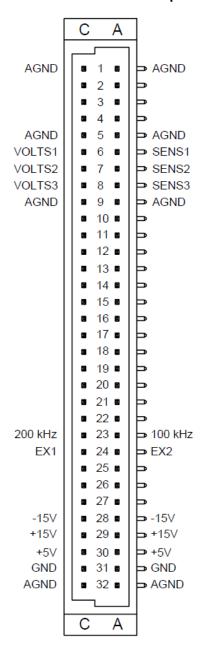
5.9.2. Specifications

| Model | E-515.01 | E-515.03 |
|-----------------------|---|---|
| Function | Display Module for Piezo Voltage and Position | Display Module for Piezo Voltage and Position |
| Channels | 1 | 3 |
| Display linearity | 0.1% | 0.1% |
| Display | 1 x 3½ digits | 3 x 3½ digits |
| Dimensions | 21HP/3U | 21HP/3U |
| Mass | 0.3 kg | 0.3 kg |
| Operating voltage | E-500/E-501 system | E-500/E-501 system |
| Operating temperature | +5°C to +50°C | +5°C to +50°C |

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5.9.3. Pin Assignment

E-515.01 and E-515.03 32-pin connector, DIN 41612, male



5.9.4. Display Adjustment

NOTICE



Damage from electrostatics!

The E-500/E-501 system contains electrostatic sensitive devices (EGB) and can be damaged if handled improperly.

- Avoid touching components, pins and PCB tracks.
- > Before touching an electronic component, discharge yourself of any electric charges:
 - While working, wear an antistatic wrist strap or
 - Briefly touch a conducting, grounded object.

INFORMATION

If ordered as part of a E-500/E-501 system or if PI is informed about the application, E-515.01 and E-515.03 display modules come preset (range, decimal places).

Making the display adjustment elements accessible

Only remove modules from the chassis when you are authorized and have the corresponding qualifications.

- 1. Remove the E-500/E-501 system from the power source by pulling the power plug.
- 2. Wait a minute to be sure that any residual voltage has dissipated.
- 3. Remove the E-515 module from the chassis:
 - a) Loosen the four Phillips screws on the front panel.
 - b) Using the grip at the bottom of the front panel, pull the module out of the chassis.

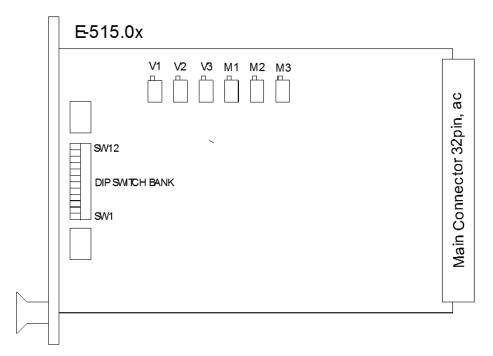


Fig. 31: Location of display adjustment elements on the E-515.0x display module

| Potentiometers: | DIP Switch Settings |
|---|--|
| Reading adjustments: | Setting the decimal point: |
| V1–V3: Voltage channels 1–3 M1–M3 Microns channels 1–3 | S1–S3: Micron channel 3 S4: Volt channel 3 S5–S7: Micron channel 2 S8: Volt channel 2 S9–S11: Micron channel 1 |

S12:

Volt channel 1

5.10. E-517 Computer Interface and Display Module

INFORMATION

See the E-517 User Manual (PZ214E) for a detailed description.

5.10.1. Front Panel Elements



Fig. 32: E-517.i3 interface / display module, singlechannel E-517.i1 models have identical front panels but show only one channel in the display



Fig. 33: E-517.i30 interface / display module, single-channel E-517.i10 models have identical front panels but show only one channel in the display

| Labeling | Туре | Function |
|--|---------------------------------|---|
| o III s 100 £517 1 8668.610 655.755um 2 8686.270 882.883um 3 8688.190 881.978um | LCD display | See "Display Screens" in the E-517 user manual for details. |
| Digital In/Out | MDR14 socket | Digital input and output lines; can be used to trigger external devices and to send start and synch. signals to the wave generator(s). See "Digital In/Out Socket" in the E-517 user manual for the availability of the lines and for pinout. |
| RS-232 | Sub-D 9-pin panel plug, male | Serial connection to host PC. See "RS-232 Socket" in the E-517 user manual for pinout. |
| | Trackball | Display selection, device configuration and triggering of ONLINE motion. See "Trackball Functions" in the E-517 user manual for details. |
| • | USB-B socket | Universal Serial Bus for connection to host PC. See "USB Connection" in the E-517 user manual for more information. |
| E-517.i3 and E- 517.i1 only: GPIB/IEEE488 | IEEE-488 micro ribbon socket | General Purpose Interface Bus (GPIB) for connection to host PC. See "GPIB Connection" in the E-517 user manual for more information. |
| <u> </u> | RJ45 socket | Network connection over TCP/IP. See "TCP/IP Connection" in the E-517 user manual for more information. |

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5.10.2. Specifications

| | E-517.i1, E-517.i10 | E-517.i3, E-517.i30 |
|-----------------------------|--|--|
| Function | Digital operation module | Digital operation module |
| Channels | 1 | 3 |
| Processor | DSP 60 MHz | DSP 60 MHz |
| Sampling rate, sensor | 25 kHz, 8-times oversampling | 25 kHz, 8-times oversampling |
| Thermal drift | Stability: 0.2 mV | Stability: 0.2 mV |
| Linearity @ nominal range | 0.01% | 0.01% |
| Resolution | DAC: 24 bit, ±12 V ADC: 18 bit, sampling | DAC: 24 bit, ±12 V ADC: 18 bit, sampling |
| Interfaces and operation | | |
| Interfaces/communication | Ethernet (TCP/IP), USB, RS-232, IEEE 488 (E-517.i1 only) | Ethernet (TCP/IP), USB, RS-232, IEEE 488 (E-517.i3 only) |
| I/O ports | 1 trigger input 1 trigger output 5 V MDR14 connector | 3 trigger inputs 3 trigger outputs 5 V MDR14 connector |
| Command set | PI General Command Set (GCS) | PI General Command Set (GCS) |
| User software | PIMikroMove | PIMikroMove |
| Software drivers | Lab VIEW drivers, Windows and Linux Libraries (DLL) | Lab VIEW drivers, Windows and Linux Libraries (DLL) |
| Supported functionality | Wave generator, data recorder, macro programming | Wave generator, data recorder, macro programming |
| Display | LCD display for monitor signals (position and voltage), states and trackball menus | LCD display for monitor signals (position and voltage), states and trackball menus |
| Manual control | Operation via trackball | Operation via trackball |
| Miscellaneous | | |
| Operating temperature range | +5° to +50° C | +5° to +50° C |
| Dimensions | 21HP/3U | 21HP/3U |
| Mass | 0.37 kg | 0.37 kg |
| Operating voltage | E-500/E-501 system; +5 V, 1 A ±15 V, 0.5 A | E-500/E-501 system; +5 V, 1 A ±15 V, 0.5 A |

5.10.3. Pin Assignment

32-pin connector, DIN 41612, male

| Row | Pin a | Pin c |
|-----|-------------------------|----------------------|
| 1 | AGND | AGND |
| 2 | IN: ch1 | OUT: ch1 |
| 3 | IN: ch2 | OUT: ch2 |
| 4 | IN: ch3 | OUT: ch3 |
| 5 | AGND (analog) | AGND (analog) |
| 6 | IN: Sensor Monitor ch1 | IN: PZT Monitor ch1 |
| 7 | IN: Sensor Monitor ch2* | IN: PZT Monitor ch2* |
| 8 | IN: Sensor Monitor ch3* | IN: PZT Monitor ch3* |
| 9 | AGND (analog) | AGND (analog) |
| 10 | nc | nc |
| 11 | I ² C SCL | I ² C SDA |
| 12 | nc | nc |
| 13 | VC/EC ch1 (servo mode) | Overflow ch1 |
| 14 | VC/EC ch2* (servo mode) | Overflow ch2* |
| 15 | VC/EC ch3* (servo mode) | Overflow ch3* |
| 16 | On Target ch1 | nc |
| 17 | On Target ch2* | nc |
| 18 | On Target ch3* | nc |
| 19 | nc | nc |
| 20 | nc | nc |
| 21 | nc | nc |
| 22 | nc | nc |
| 23 | Sync_100k | Sync_200k |
| 24 | nc | nc |
| 25 | nc | nc |
| 26 | nc | nc |
| 27 | nc | nc |
| 28 | -15 V | -15 V |
| 29 | +15 V | +15 V |
| 30 | +5 V (VCC) | +5 V (VCC) |
| 31 | GND (VCC) | GND (VCC) |
| 32 | AGND (analog) | AGND (analog) |

nc - no connection

AGND - Analog Ground, isolated from the GND (VCC) (pins 31ac)

^{*} on E-517.i1 and E-517.i10, lines for channels 2 and 3 should not be used

5.11. Dummy Modules

Your E-500/E-501 system may be equipped with one or more dummy modules:

E-595.00 Replaces E-509.xx sensor modules (all types)

E-596.00 Replaces the E-517 interface / display module (or the E-515 display module), if E-509

modules for SGS sensors are installed

E-596.10 Replaces the E-517 interface / display module (or the E-515 display module), if E-509

modules for capacitive sensors are installed

The purpose of these dummies is to complete the internal circuitry and the front panel of the chassis.

INFORMATION

Your E-500/E-501 system may be equipped with one or more dummy modules. Do not operate your E-500/E-501 system when (dummy) modules are removed. Without the dummy module(s), the system will malfunction because no Control In signal can be feed into the amplifier module due to the broken circuit.

6. Integrating Modules in Third-Party Systems

6.1.1. Safety Measures for Integration in Third-Party Systems

DANGER



High Voltage!

- Only authorized and qualified personnel must install, operate, maintain and clean the modules of the E-500/E-501 series.
- > Remove the third-party system from the power source before integrating modules of the E-500/E-501 series.

The amplifier modules of the E-500/E-501 series output up to 130 V (E-503, E-504, E-505, E-506) or up to 1100 V (E-508). Touching this High Voltage can result in serious or even lethal injury due to electric shock.

- Operate an amplifier module only when it is installed in a suitable chassis and connected to a protective earth conductor via pins 32a and 32c of the 32-pin connector, DIN 41612, male.
 - Make sure that the resistance of the protective earth conductor is < 1 Ω at 25 A on all interfaces relevant for the function of the protective earth conductor.
 - If the protective earth conductor has to be removed (e.g. in case of system modifications), reconnect the protective earth conductor before the next start-up of the module.
- ➤ When you operate E-504, E-505 or E-506 amplifier modules, do not touch pins 6a, 6c, 8a and 8c of the 32-pin connector since the piezo voltage is output on these pins (in addition to the output on the **PZT** socket of the front panel).

NOTICE



Damage from electrostatics!

The E-500/E-501 system contains electrostatic sensitive devices (EGB) and can be damaged if handled improperly. When operated without chassis, the modules of the E-500/E-501 system can emit electrical, magnetic or electromagnetic fields which interfere with the environment.

- Avoid touching components, pins and PCB tracks.
- > Before touching an electronic component, discharge yourself of any electric charges:
 - While working, wear an antistatic wrist strap or
 - Briefly touch a conducting, grounded object.
- When modules of the E-500/E-501 series are installed in a third-party chassis, make sure that the system complies with the EMC requirements.

6.1.2. Supply Power for the Modules

The supply power must be stable within a range of 2 % of the nominal value.

For stable supply power with dynamic operation of high piezo loads, the power supply must be equipped with a sufficiently dimensioned buffer capacitor. The required capacitance of the buffer can be approximated as follows:

Buffer capacitance = 10 x piezo load

6.1.3. Amplifier Modules: Closing the Circuit

In order to feed the Control In signal (DC-Offset potentiometer and/or Control Input) into the amplifier, short the following pins:

E-504, E-505, E-506, E-508 → pin 2c to 4a

E-503 → pin 2c to 4a; pin 10c to 12a; pin 18c to 20a

Otherwise the output voltage of the amplifier would go to its positive / negative limit.

7. Maintenance

7.1. Cleaning

NOTICE



Short circuits or flashovers!

The E-500/E-501 system contains electrostatic sensitive devices that can be damaged by short circuits or flashovers when cleaning fluids enter the case.

- ➢ Before cleaning, remove the E-500/E-501 system from the power source by pulling the power plug.
- Prevent cleaning fluid from entering the case.

The housing surfaces of the device can be cleaned using mild detergents or disinfectant solutions. Organic solvents must not be used.

7.2. AC Power and Line Fuses

DANGER



Risk of electric shock!

The E-500/E-501 system requires a supply voltage of 100 to 120 VAC or 220 to 240 VAC (line voltage). Touching the line voltage can result in serious or even lethal injury due to electric shock.

> Remove the power cord from the E-500/E-501 system before you change the line fuses.

INFORMATION

Both line fuses of the E-500/E-501 system are active.

Check both fuses if there is a fault.

The power connection and line fuses are located on the rear panel of the chassis. To access the line fuses, proceed as follows:

- 1 Switch off the E-500/E-501 system and remove the power cord.
- 2 Wait a minute to be sure that any residual voltage has dissipated.
- 3 Pry open the door that covers the fuse carrier and pry out the fuse carrier (see figures below).

4 Be sure to replace both fuses with fuses of the suitable type:

| Model | Line voltage ranges and fuse values | |
|-----------|---|--|
| E-500.00 | 100 to 240 V~ 2 x IEC T2AH, 250 V | |
| E-501.00 | 100 to 120 V~ 2 x IEC T2AH, 250 V 220 to 240 V~ 2 x IEC T1AL, 250 V | |
| E-500Kxxx | see product-specific documentation or nameplate label on device | |
| E-501Kxxx | see product-specific documentation or nameplate label on device | |

Note: IEC-standard fuses are designed to carry the nominal current indefinitely. Other fuse rating standards differ.

5 Reinstall the carrier and close the door









8. Customer Service

For inquiries and orders, contact your PI sales engineer or send us an e-mail (mailto:info@pi.ws).

If you have questions concerning your system, have the following information ready:

- Product codes and serial numbers of all products in the system
- Firmware version of the controller (if present)
- Version of the driver or the software (if present)
- Operating system on the PC (if present)

The latest versions of the relevant user manuals for your system are available for download on our website (www.pi.ws).

9. Old Equipment Disposal

In accordance with the applicable EU law, electrical and electronic equipment may not be disposed of with unsorted municipal wastes in the member states of the EU.

When disposing of your old equipment, observe the international, national and local rules and regulations.

To meet the manufacturer's product responsibility with regard to this product, Physik Instrumente (PI) GmbH & Co. KG ensures environmentally correct disposal of old PI equipment that was first put into circulation after 13 August 2005, free of charge.

If you have old PI equipment, you can send it postage-free to the following address:

Physik Instrumente (PI) GmbH & Co. KG

Auf der Römerstr. 1

D-76228 Karlsruhe, Germany



10. Appendix

10.1. Lifetime of PICMA® Actuators

The following factors which can have an impact on the actuator lifetime must be taken into consideration: Applied voltage, temperature and relative humidity.

The effect of each individual factor on the lifetime can be read off the diagrams shown below. The lifetime calculated in hours simply results as the product of all three values read off the diagrams.

The impact that the applied voltage has, is particularly important. With decreasing voltage the lifetime increases exponentially. This must always be taken into consideration in an application. The recommended maximum range of the control input voltage for the E-500/E-501 system therefore is -2 to 12 V, resulting in a piezo voltage range of -20 to 120 V. A control input range of -3 to 13 V is possible (results in -30 to 130 V piezo voltage), but will reduce the actuator lifetime accordingly.

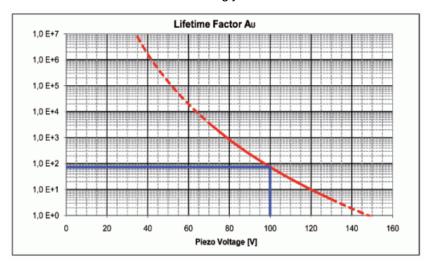


Fig. 34: Interdependency between the mean MTTF of a PICMA® actuator and the value of the voltage applied

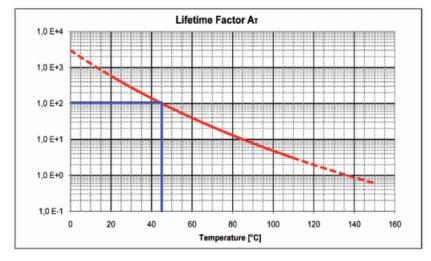


Fig. 35: Interdependency between the mean MTTF of a PICMA® actuator and the ambient temperature

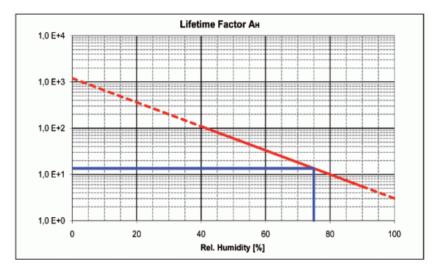


Fig. 36: Interdependency between the mean MTTF of a PICMA® actuator and the relative humidity

Example

The simple formula MTTF = AU * AT * AF provides a quick estimate of the reliability in hours. In concrete terms: The values for 75% RH (AF=14), 100 VDC (AU=75) and 45 °C (AT=100) result in an approximate MTTF of 105,000 h, i.e. more than 11 years (see markings on the diagrams).

Read the "Tutorial: Piezoelectrics in Positioning" in the PI Catalog for detailed information.

10.2. How to Measure the Amplifier Output of E-504 Modules

The innovative, efficient circuitry of the E-504 amplifier module reduces power consumption and heat dissipation, especially in dynamic applications. Working with an internal switching frequency of 100 kHz, charge is transferred to the piezo actuator using low-loss PWM techniques. The ripple of the amplifier output is <100 mVpp at 100 kHz. But when measuring the amplifier output signal with low sampling rate and small bandwidth (e.g. with a digital oscilloscope), aliasing will occur and distort the measurement result. In digital signal processing, aliasing refers to an effect that the signal reconstructed from samples is different than the original continuous signal when the sampling rate is too low. With the E-504 amplifier output, this means that a low-frequency signal seems to be measured which is not present at all.

Example:

When a 91 Hz signal is sampled with 100 Hz sampling rate, the result seems to be a 9.1 Hz signal (see figure below).

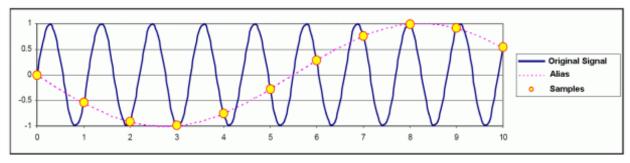


Fig. 37: Signal digitization with too low sample rate (time in 1/100 s): Original signal = 91 Hz and sampling rate = 100 Hz; the result is mistaked as a 9.1 Hz signal ("Alias")

To avoid aliasing, the sampling rate must be at least twice as high as the highest frequency in the signal to be sampled (according to the Nyquist–Shannon sampling theorem). I.e. with

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an amplifier switching frequency of 100 kHz, the sampling rate must be 200 kHz or higher. If the sampling rate provided by your oscilloscope is not high enough, use a low-pass filter at the oscilloscope input to eliminate frequencies above 100 kHz. Alternatively, you can use an analog oscilloscope or perform high-resolution measurements in the lower frequency range.

When following those instructions, you will obtain valid measurement results.

10.3. EC Declaration of Conformity

For the E-500/E-501, an EC declaration of conformity according to the following European directives was issued:

2006/95/EC, Low Voltage Directive (LVD)

2004/108/EC, EMC Directive

2011/65/EC, RoHS Directive

The applied standards certifying the conformity are listed below. Electromagnetic Emission: EN 61000-6-3:2007, EN 55011:2009

Electromagnetic Immunity: EN 61000-6-1:2007 Safety (Low Voltage Directive): EN 61010-1:2010

If electrical equipment is intended to be integrated in other electrical equipment: The user is responsible for compliant connection of the electrical equipment when implementing the total system.





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